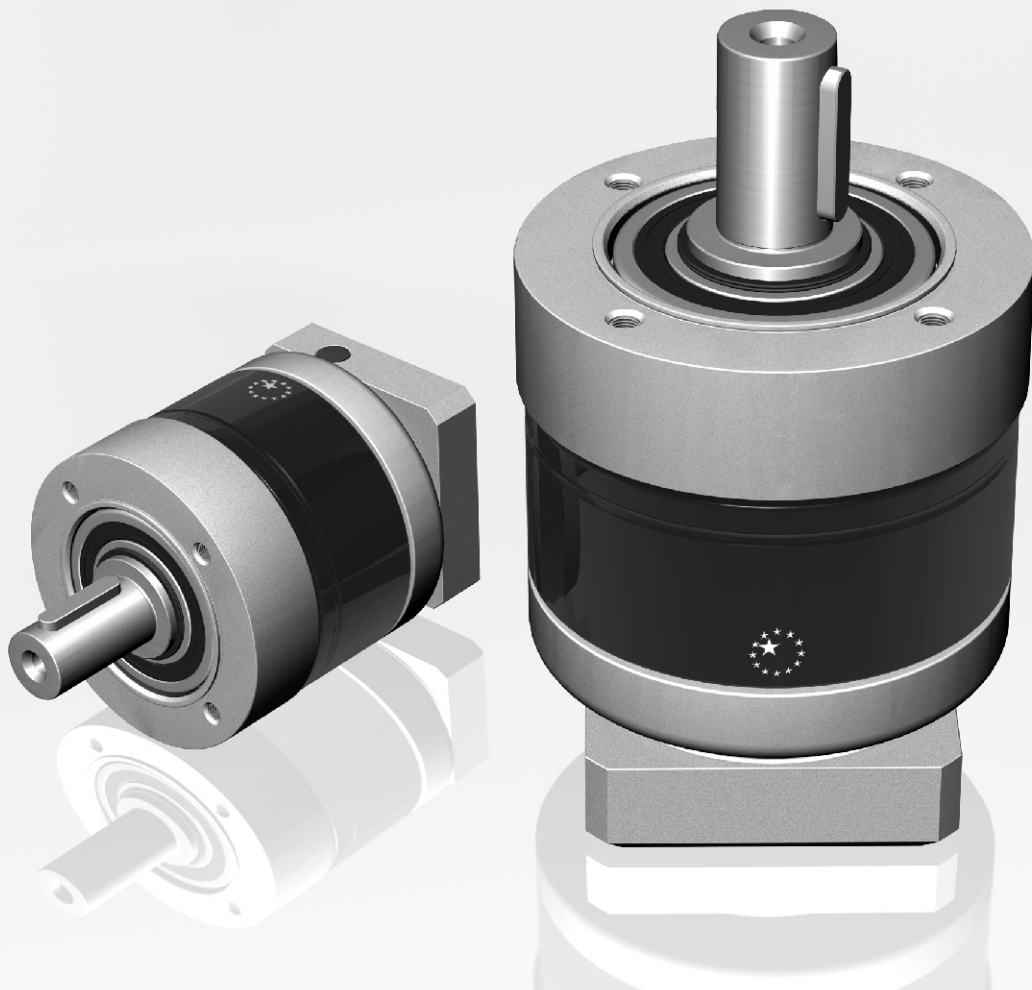




APEX DYNAMICS, INC.

PGII - SERIES
PLANETARY GEARBOX
NEW GENERATION



PGII Series

► Features:

Economic

High efficiency

Low noise

Reduced backlash

Optimized Inertia moment

Limited temperature rise

Long service life

Flexible mounting diameters

Minimized size and weight

Your motor's perfect match!!

The brand new APEX PII series. The PII series is an economic high precision planetary gearbox with excellent performance and quality. Our innovative PII series design features minimal size, light weight and high efficiency.

► Ordering Code

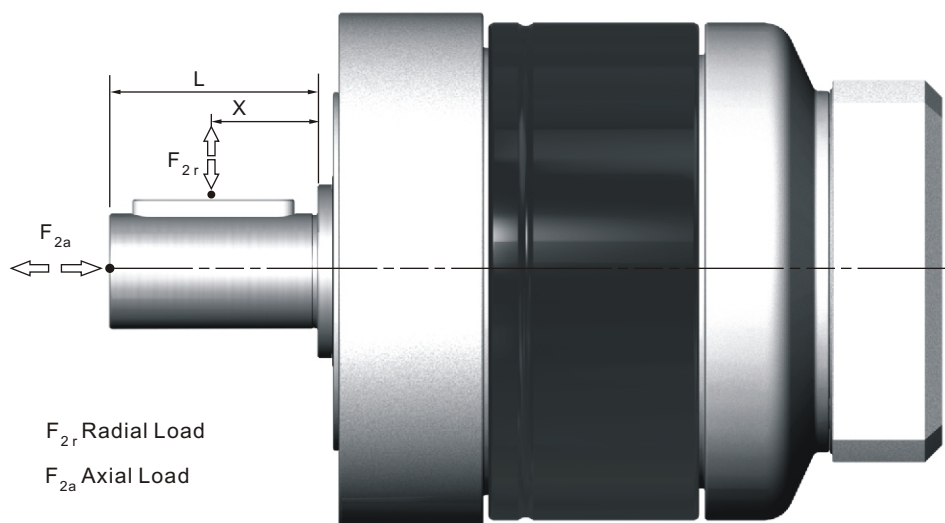
PGII 090	—	010 — ⁽²⁾	/	MOTOR
				Motor Designation: Manufacture Type And Model
				Ratio ⁽¹⁾ : 1 stage: 3, 4, 5, 7, 10 2 stage: 15, 16, 20, 25, 30, 35, 40, 50, 70, 100
Gear Size: PGII: PGII040, PGII060, PGII080, PGII120, PGII160				

Ordering Example : PGII 090-010 / SIEMENS 1FT6 041-4AF71
PAII090-010-S1 / SIEMENS 1FT6 041-4AF71

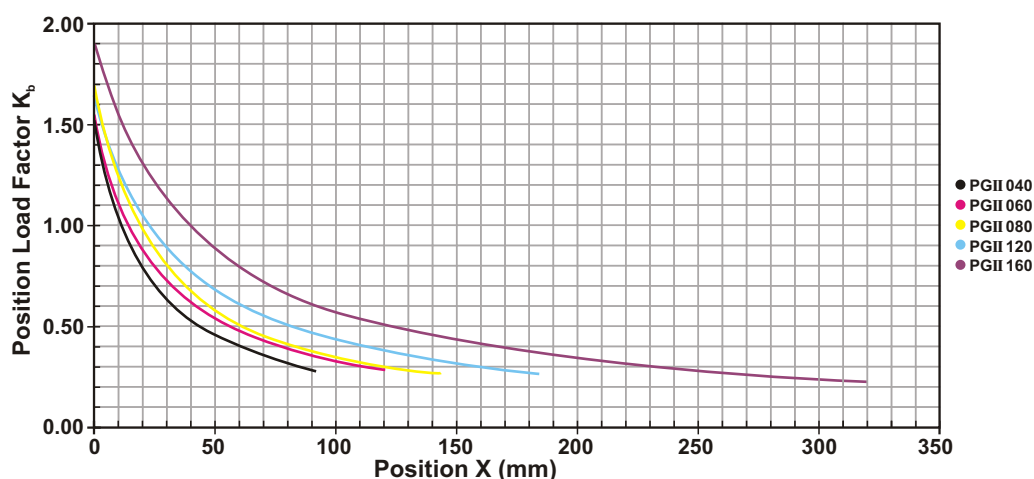
(1) Other ratios are available, please contact APEX.

(2) For PSII, PEII and PGII series, the output shaft with key (S2) is standard.
 For PAII series, the S1 and S2 are both available.

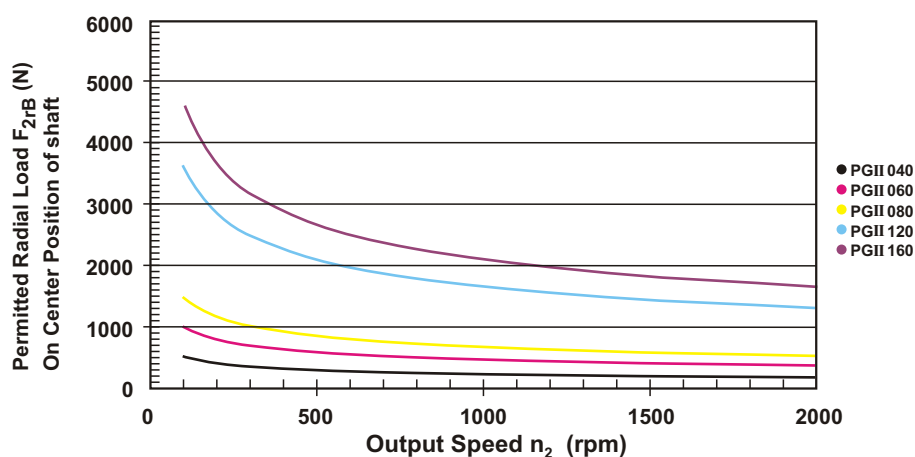
Permitted Radial And Axial Loads On Output Shaft



The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings.



If radial force F_{2r} is not exerted on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$, the permitted radial and axial loads can be calculated by the position load factor K_b on the above diagram.



Permitted radial load F_{2r} on center of output shaft $X = 1/2 \times L$ for various output speeds. Values provided are for 20,000 hours^(*) life.

(*) For Continuous Operation (S1), the service life reduced to 50%.

PGII Series Specifications

PGII 040			1-stage					2-stage									
			Ratio ^{(1) (2)}					Ratio ^{(1) (2)}									
			3	4	5	7	10	15	16	20	25	30	35	40	50	70	100
Nominal Output Torque T _{2N}	Nm		16	16	15	12	10	15	16	16	15	15	12	16	15	12	10
Emergency Stop Torque T _{2NOT}	Nm		3 times T _{2N}														
Max. Acceleration Torque T _{2B}	Nm		29	29	27	22	18	28	29	29	27	27	22	29	27	22	18
No Load Running Torque ⁽⁸⁾	Nm		0.05					0.05									
Backlash ⁽³⁾	arcmin		≤ 8					≤ 10									
Torsional Rigidity	Nm/arcmin		0.5					0.5									
Nominal Input Speed n _{1N}	rpm		4,500														
Max. Input Speed n _{1B}	rpm		8,000														
Max. Radial Load F _{2rB} ⁽⁴⁾	N		520														
Max. Axial Load F _{2aB} ⁽⁴⁾	N		260														
Service Life ⁽⁷⁾	hr		20,000														
Operating Temperature	° C		0° C~ +90° C														
Lubrication			Synthetic lubrication grease														
Degree of Protection			IP65														
Mounting Position			All directions														
Running Noise ^{(6) (8)}	dB(A)		≤ 60														
Efficiency η	%		≥ 97%					≥ 94%									
Weight	kg		Ø ⁽⁵⁾ ≤8, 11, 14= 0.7					Ø ⁽⁵⁾ ≤8, 11, 14= 0.8									
Moment of Inertia J ₁	kg.cm ²	Ø ⁽⁵⁾ ≤8	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
		Ø ⁽⁵⁾ ≤11	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16
		Ø ⁽⁵⁾ ≤14	0.2	0.2	0.19	0.19	0.19	0.19	0.19	0.2	0.19	0.19	0.19	0.19	0.19	0.19	0.19

(1) Ratio ($i = N_{in} / N_{out}$)

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm

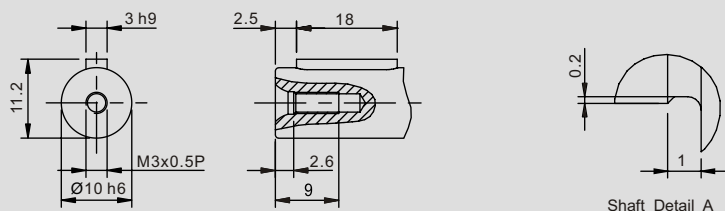
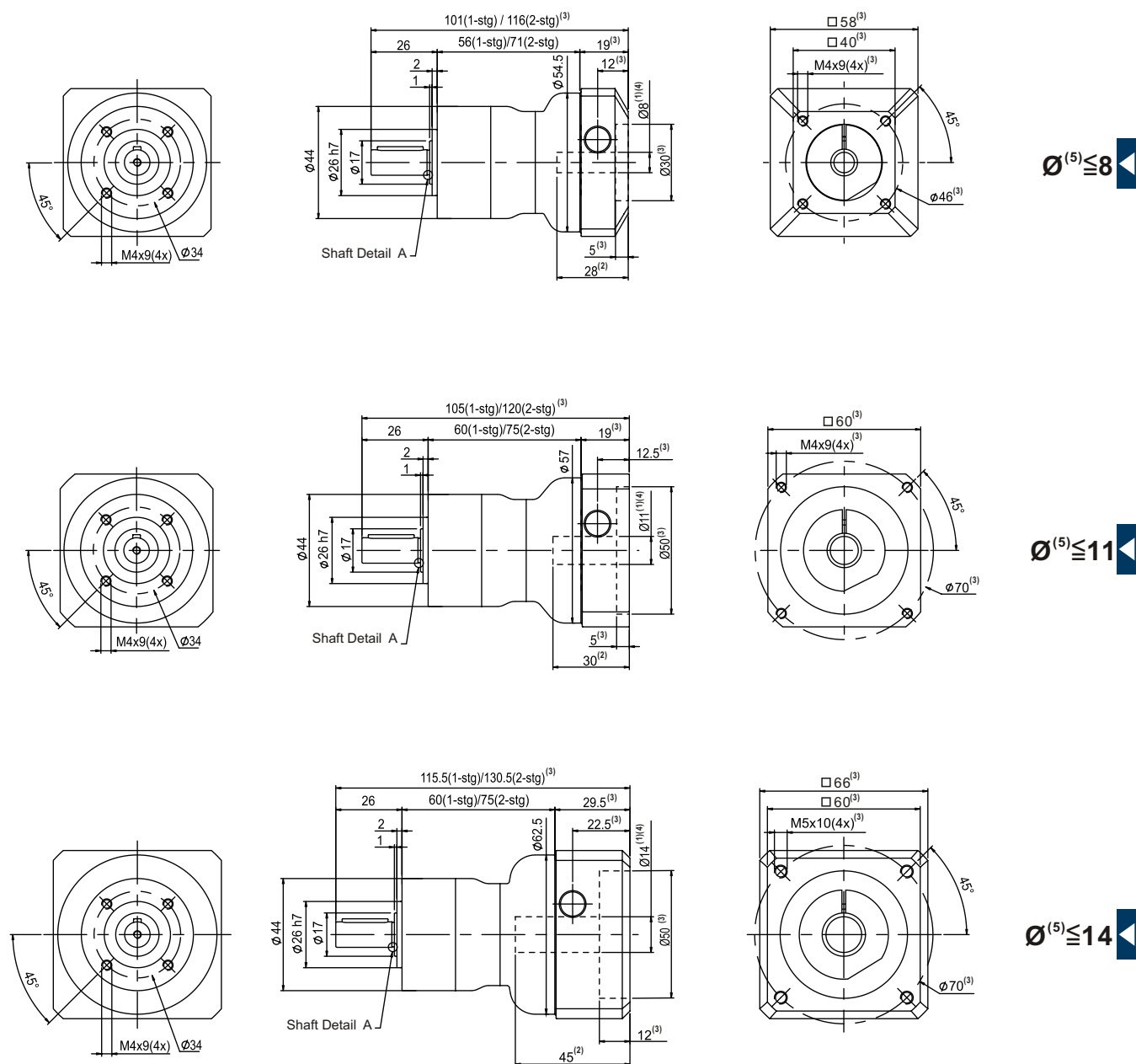
(5) $\varnothing$ = Input shaft diameter

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension



- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

PGII 060		1-stage					2-stage									
		Ratio ^{(1) (2)}					Ratio ^{(1) (2)}									
		3	4	5	7	10	15	16	20	25	30	35	40	50	70	100
Nominal Output Torque T _{2N}	Nm	42	42	40	35	27	40	42	42	40	40	35	43	40	35	27
Emergency Stop Torque T _{2NOT}	Nm	3 times T _{2N}														
Max. Acceleration Torque T _{2B}	Nm	76	76	72	63	49	72	76	76	72	72	63	77	72	63	49
No Load Running Torque ⁽⁸⁾	Nm	0.1					0.1									
Backlash ⁽³⁾	arcmin	≤ 7					≤ 9									
Torsional Rigidity	Nm/arcmin	2					2									
Nominal Input Speed n _{1N}	rpm	4,000														
Max. Input Speed n _{1B}	rpm	6,000														
Max. Radial Load F _{2rB} ⁽⁴⁾	N	1,030														
Max. Axial Load F _{2aB} ⁽⁴⁾	N	515														
Service Life ⁽⁷⁾	hr	20,000														
Operating Temperature	° C	0° C~ +90° C														
Lubrication		Synthetic lubrication grease														
Degree of Protection		IP65														
Mounting Position		All directions														
Running Noise ^{(6) (8)}	dB(A)	≤ 62														
Efficiency η	%	≥ 97%					≥ 94%									
Weight	kg	Ø ⁽⁵⁾ ≤8, 11, 14= 1.2 Ø ⁽⁵⁾ ≤19= 1.9					Ø ⁽⁵⁾ ≤8, 11, 14= 1.5 Ø ⁽⁵⁾ ≤19= 2.2									
Moment of Inertia J ₁	kg.cm ²	Ø ⁽⁵⁾ ≤8	0.12	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
		Ø ⁽⁵⁾ ≤11	0.19	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16
		Ø ⁽⁵⁾ ≤14	0.22	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2
		Ø ⁽⁵⁾ ≤19	1.53	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51	1.51

(1) Ratio ($i = N_{in} / N_{out}$)

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm

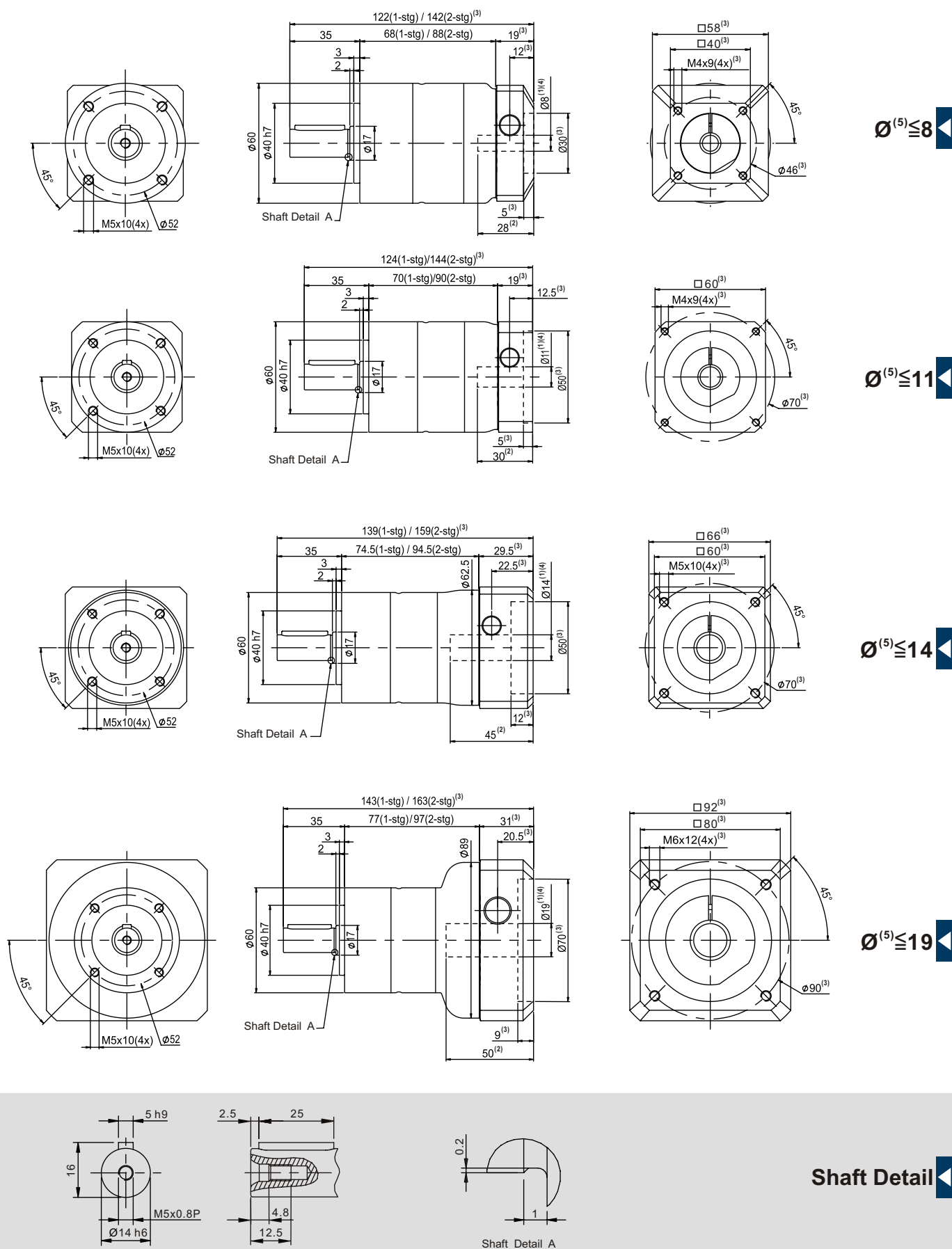
(5) $\emptyset$ = Input shaft diameter

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension



- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) $\varnothing$ = Input shaft diameter.

PGII Series Specifications

PGII 080		1-stage					2-stage										
		Ratio ^{(1) (2)}					Ratio ^{(1) (2)}										
		3	4	5	7	10	15	16	20	25	30	35	40	50	70	100	
Nominal Output Torque T _{2N}	Nm	110	113	118	96	68	109	116	116	123	108	100	117	123	100	70	
Emergency Stop Torque T _{2NOT}	Nm	3 times T _{2N}															
Max. Acceleration Torque T _{2B}	Nm	198	203	212	173	122	196	208	208	221	195	179	210	221	179	127	
No Load Running Torque ⁽⁸⁾	Nm	0.4					0.3										
Backlash ⁽³⁾	arcmin	≤ 6					≤ 8										
Torsional Rigidity	Nm/arcmin	8					8										
Nominal Input Speed n _{1N}	rpm	3,600															
Max. Input Speed n _{1B}	rpm	6,000															
Max. Radial Load F _{2rB} ⁽⁴⁾	N	1,570															
Max. Axial Load F _{2aB} ⁽⁴⁾	N	785															
Service Life ⁽⁷⁾	hr	20,000															
Operating Temperature	° C	0° C~ +90° C															
Lubrication		Synthetic lubrication grease															
Degree of Protection		IP65															
Mounting Position		All directions															
Running Noise ^{(6) (8)}	dB(A)	≤ 64															
Efficiency η	%	≥ 97%					≥ 94%										
Weight	kg	Ø ⁽⁵⁾ ≤ 14= 2.4 Ø ⁽⁵⁾ ≤ 19, 24, 28= 3.4					Ø ⁽⁵⁾ ≤ 14, 19 = 3.9 Ø ⁽⁵⁾ ≤ 24, 28 = 4.3										
Moment of Inertia J ₁	kg.cm ²	Ø ⁽⁵⁾ ≤ 14	0.36	0.24	0.22	0.21	0.2	0.22	0.24	0.22	0.22	0.2	0.22	0.2	0.2	0.2	0.2
		Ø ⁽⁵⁾ ≤ 19	1.7	1.58	1.56	1.55	1.54	1.56	1.58	1.56	1.56	1.54	1.56	1.54	1.54	1.54	1.54
		Ø ⁽⁵⁾ ≤ 24	2.24	2.12	2.1	2.09	2.09	2.1	2.12	2.1	2.1	2.09	2.1	2.09	2.09	2.09	2.09
		Ø ⁽⁵⁾ ≤ 28	2.68	2.55	2.53	2.52	2.52	2.53	2.55	2.53	2.53	2.52	2.53	2.52	2.52	2.52	2.52

(1) Ratio ($i = N_{in} / N_{out}$)

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm

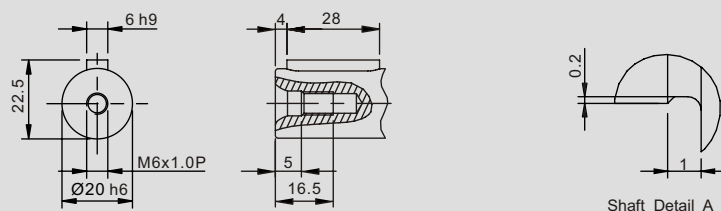
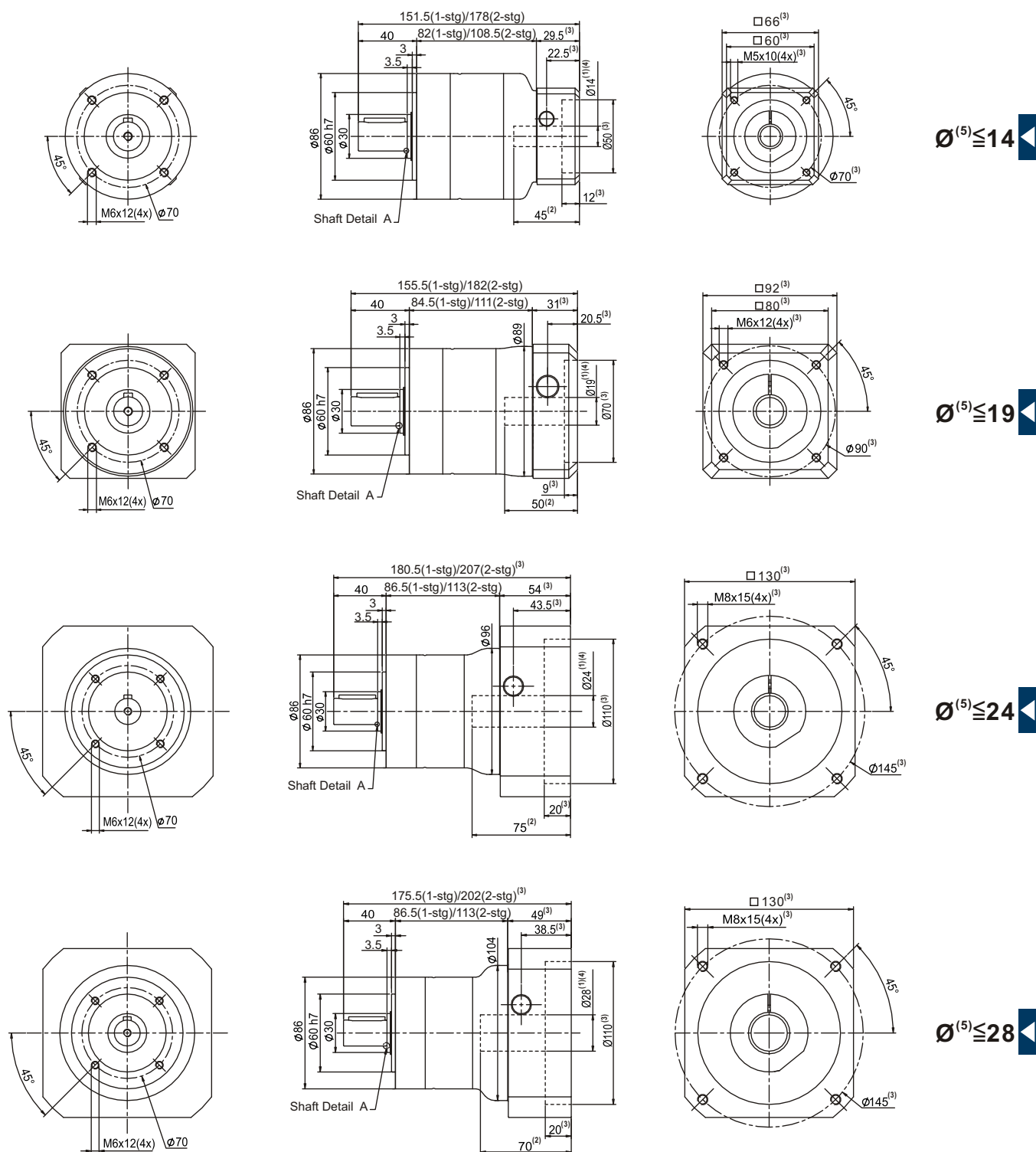
(5) $\varnothing$ = Input shaft diameter

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension



- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

PGII 120			1-stage					2-stage									
			Ratio ^{(1) (2)}					Ratio ^{(1) (2)}									
			3	4	5	7	10	15	16	20	25	30	35	40	50	70	100
Nominal Output Torque T _{2N}	Nm	217	223	220	198	155	213	228	230	228	212	206	232	228	206	162	
Emergency Stop Torque T _{2NOT}	Nm	3 times T _{2N}															
Max. Acceleration Torque T _{2B}	Nm	391	401	396	356	279	383	411	413	411	381	370	417	411	370	291	
No Load Running Torque ⁽⁸⁾	Nm	0.8					0.4										
Backlash ⁽³⁾	arcmin	≤ 6					≤ 8										
Torsional Rigidity	Nm/arcmin	12					12										
Nominal Input Speed n _{1N}	rpm	3,600															
Max. Input Speed n _{1B}	rpm	4,800															
Max. Radial Load F _{2rB} ⁽⁴⁾	N	3,590															
Max. Axial Load F _{2aB} ⁽⁴⁾	N	1,795															
Service Life ⁽⁷⁾	hr	20,000															
Operating Temperature	° C	0° C~ +90° C															
Lubrication		Synthetic lubrication grease															
Degree of Protection		IP65 ⁽⁸⁾															
Mounting Position		All directions															
Running Noise ^{(6) (8)}	dB(A)	≤ 66															
Efficiency η	%	≥ 97%					≥ 94%										
Weight	kg	Ø ⁽⁵⁾ ≤ 19, 24, 28= 6.2 Ø ⁽⁵⁾ ≤ 32, 35= 7.8 Ø ⁽⁵⁾ ≤ 38= 11.7					Ø ⁽⁵⁾ ≤ 19, 24, 28= 8.3 Ø ⁽⁵⁾ ≤ 32, 35= 9.9 Ø ⁽⁵⁾ ≤ 38= 13.8										
Moment of Inertia J ₁	kg.cm ²	Ø ⁽⁵⁾ ≤ 19	2.2	1.73	1.65	1.61	1.6	1.65	1.73	1.65	1.65	1.6	1.65	1.6	1.6	1.6	1.6
		Ø ⁽⁵⁾ ≤ 24	2.74	2.27	2.19	2.15	2.14	2.19	2.27	2.19	2.19	2.14	2.19	2.14	2.14	2.14	2.14
		Ø ⁽⁵⁾ ≤ 28	3.17	2.7	2.62	2.58	2.57	2.62	2.7	2.62	2.62	2.57	2.62	2.57	2.57	2.57	2.57
		Ø ⁽⁵⁾ ≤ 32	7.77	7.3	7.22	7.18	7.17	7.22	7.3	7.22	7.22	7.17	7.22	7.17	7.17	7.17	7.17
		Ø ⁽⁵⁾ ≤ 35	10.8	10.3	10.2	10.2	10.2	10.2	10.3	10.2	10.2	10.2	10.2	10.2	10.2	10.2	10.2
		Ø ⁽⁵⁾ ≤ 38	14	13.5	13.4	13.4	13.4	13.4	13.5	13.4	13.4	13.4	13.4	13.4	13.4	13.4	13.4

(1) Ratio ($i = N_{in} / N_{out}$)

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm

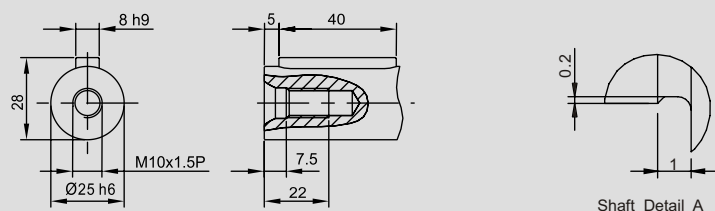
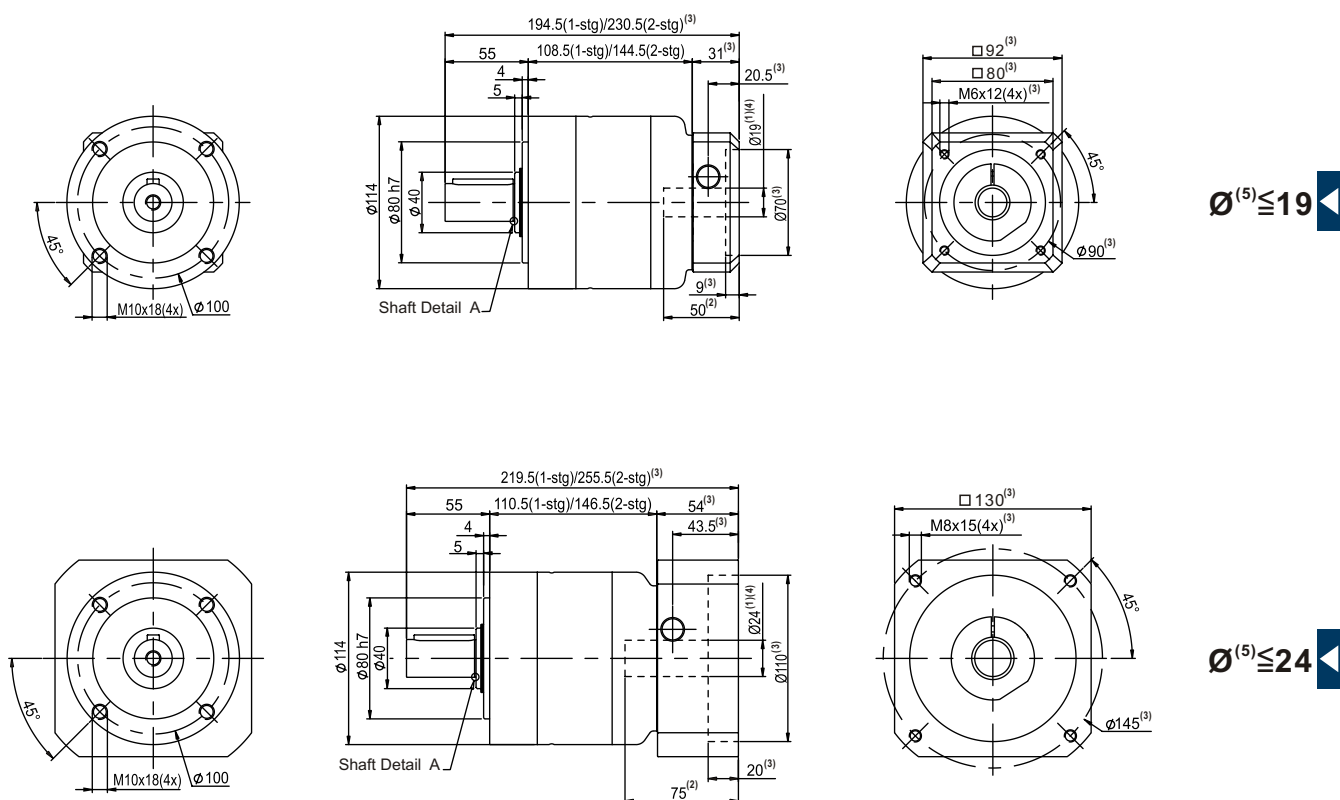
(5) $\emptyset$ = Input shaft diameter

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension

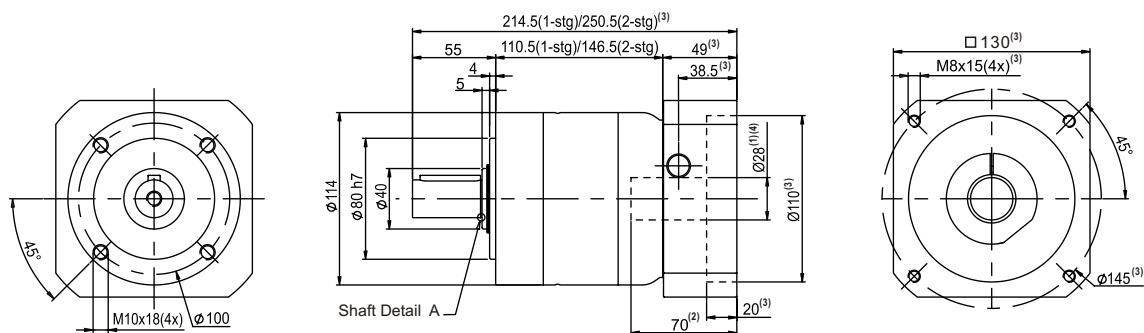


Shaft Detail

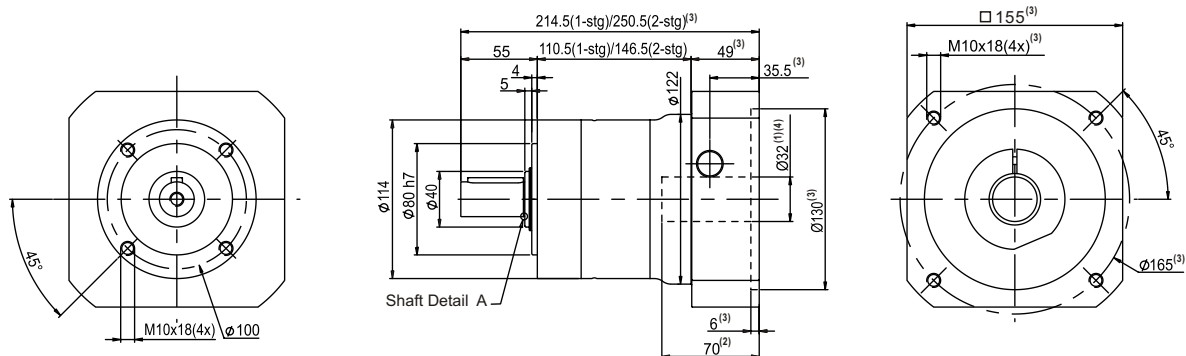
- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Dimension

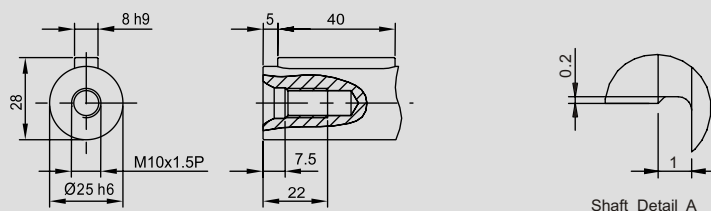
▶ $\emptyset^{(5)} \leq 28$



▶ $\emptyset^{(5)} \leq 32$



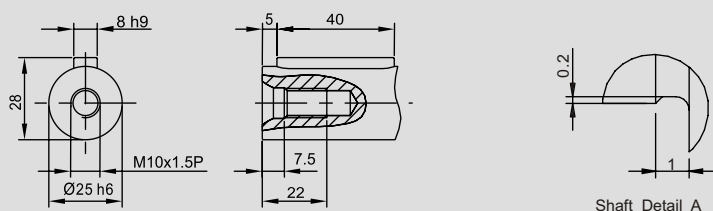
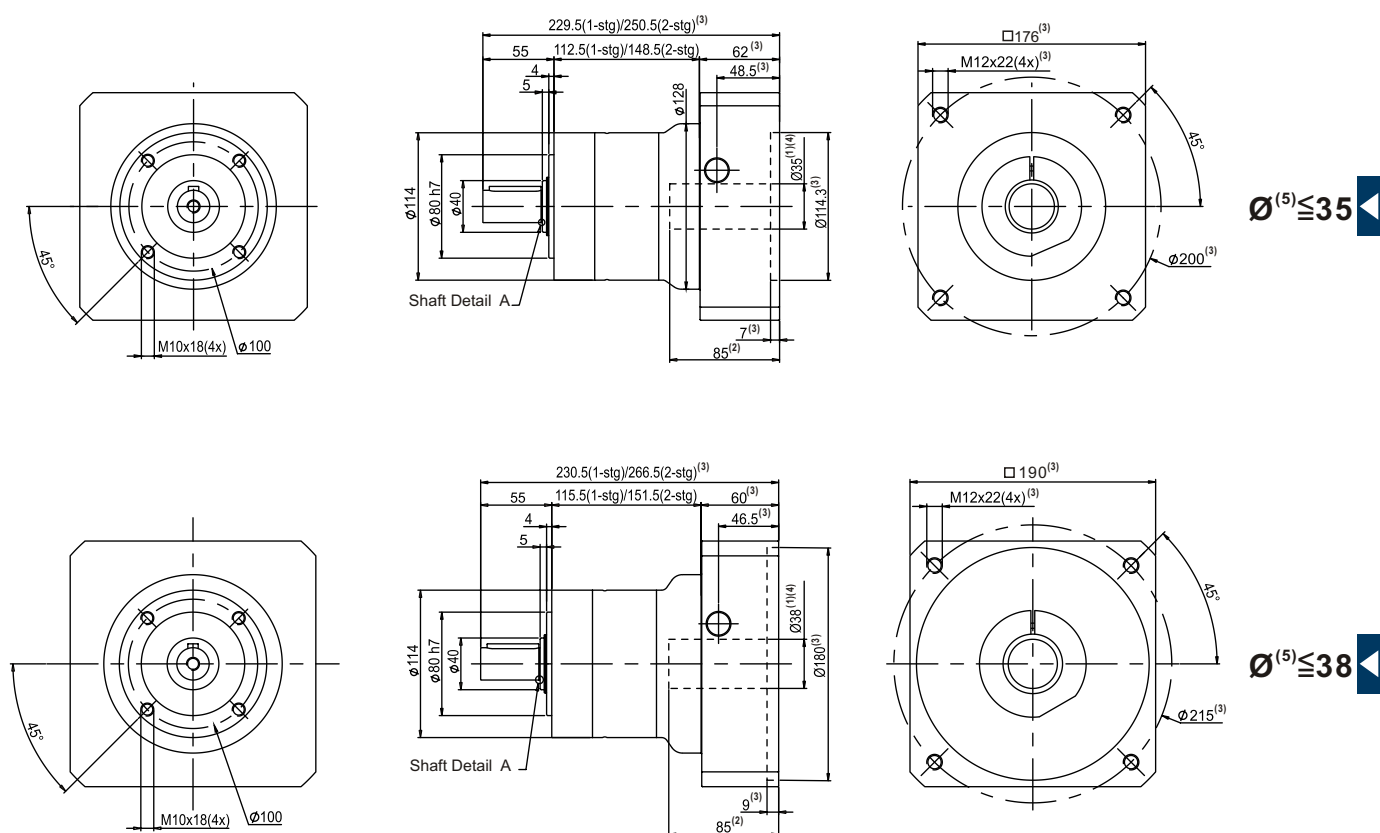
▶ Shaft Detail



Shaft Detail A

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) $\emptyset$ = Input shaft diameter.

PGII Series Dimension



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

PGII 160		1-stage					2-stage										
		Ratio ^{(1) (2)}					Ratio ^{(1) (2)}										
		3	4	5	7	10	15	16	20	25	30	35	40	50	70	100	
Nominal Output Torque T _{2N}	Nm	430	440	435	366	295	424	452	454	450	422	382	459	450	382	308	
Emergency Stop Torque T _{2NOT}	Nm	3 times T _{2N}															
Max. Acceleration Torque T _{2B}	Nm	774	792	783	659	531	763	813	817	810	759	688	827	810	688	555	
No Load Running Torque ⁽⁸⁾	Nm	2.5					0.8										
Backlash ⁽³⁾	arcmin	≤ 6					≤ 8										
Torsional Rigidity	Nm/arcmin	16					16										
Nominal Input Speed n _{1N}	rpm	2,500															
Max. Input Speed n _{1B}	rpm	3,600															
Max. Radial Load F _{2rB} ⁽⁴⁾	N	4,690															
Max. Axial Load F _{2aB} ⁽⁴⁾	N	2,345															
Service Life ⁽⁷⁾	hr	20,000															
Operating Temperature	° C	0° C ~ +90° C															
Lubrication		Synthetic lubrication grease															
Degree of Protection		IP65															
Mounting Position		All directions															
Running Noise ^{(6) (8)}	dB(A)	≤ 68															
Efficiency η	%	≥ 97%					≥ 94%										
Weight	kg	Ø ⁽⁵⁾ ≤ 24, 28= 11.5 Ø ⁽⁵⁾ ≤ 32, 35= 13.1 Ø ⁽⁵⁾ ≤ 38, 42= 17.1					Ø ⁽⁵⁾ ≤ 19, 24, 28= 15.5 Ø ⁽⁵⁾ ≤ 32, 35= 17.1 Ø ⁽⁵⁾ ≤ 38= 20.9										
Moment of Inertia J ₁	kg.cm ²	Ø ⁽⁵⁾ ≤ 19	-	-	-	-	-	1.85	2.18	1.85	1.85	1.69	1.85	1.69	1.69	1.69	1.69
		Ø ⁽⁵⁾ ≤ 24	4.52	2.73	2.4	2.26	2.23	2.4	2.73	2.4	2.4	2.23	2.4	2.23	2.23	2.23	2.23
		Ø ⁽⁵⁾ ≤ 28	4.94	3.15	2.82	2.68	2.65	2.82	3.15	2.82	2.82	2.65	2.82	2.65	2.65	2.65	2.65
		Ø ⁽⁵⁾ ≤ 32	9.7	7.91	7.58	7.44	7.41	7.58	7.91	7.58	7.58	7.41	7.58	7.41	7.41	7.41	7.41
		Ø ⁽⁵⁾ ≤ 35	12.8	11	10.7	10.5	10.5	10.7	11	10.7	10.7	10.5	10.7	10.5	10.5	10.5	10.5
		Ø ⁽⁷⁾ ≤ 38	16	14.2	13.9	13.7	13.7	13.9	14.2	13.9	13.9	13.7	13.9	13.7	13.7	13.7	13.7
		Ø ⁽⁷⁾ ≤ 42	24.5	22.7	22.4	22.2	22.2	-	-	-	-	-	-	-	-	-	-

(1) Ratio ($i = N_{in} / N_{out}$)

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm

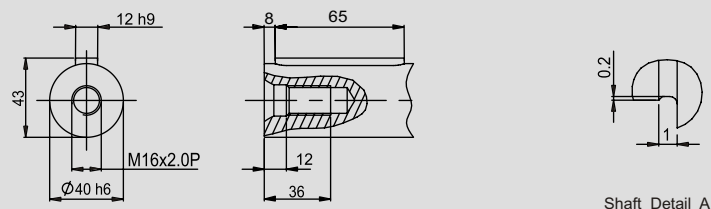
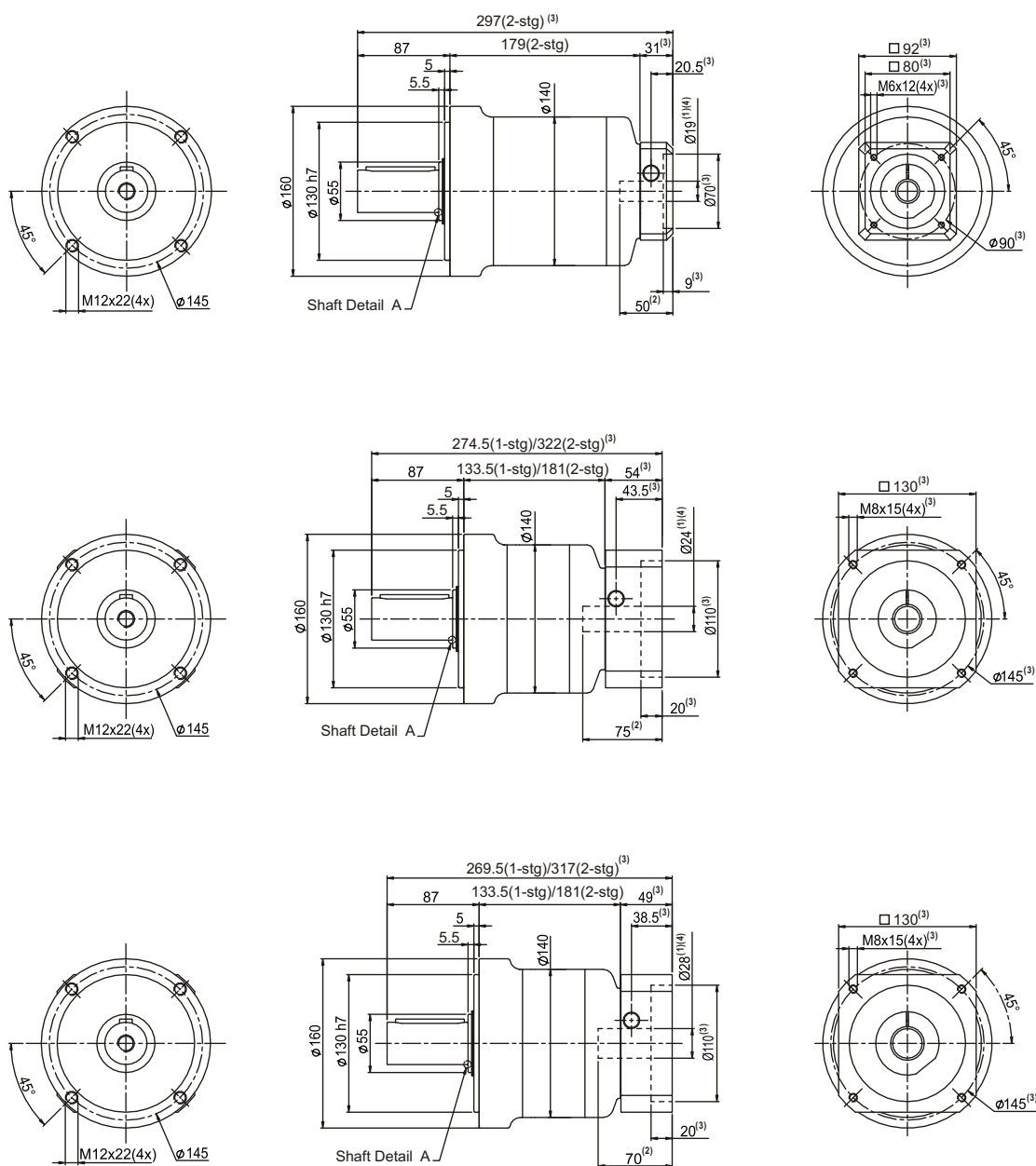
(5) $\emptyset$ = Input shaft diameter

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension

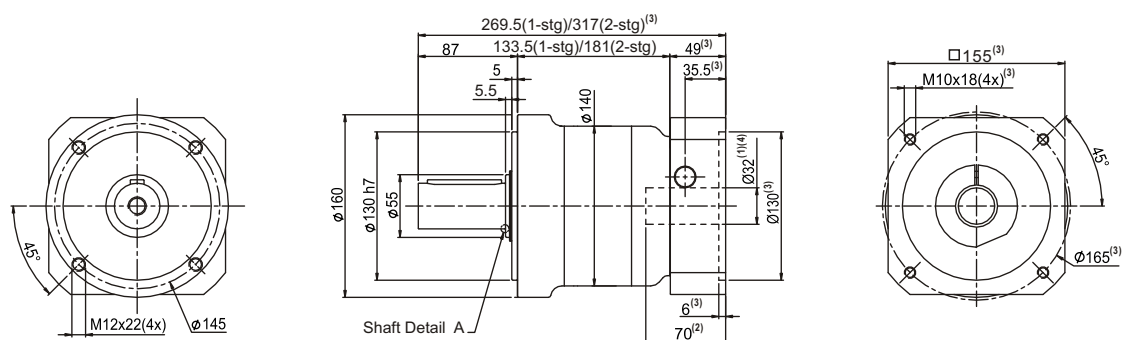


Shaft Detail

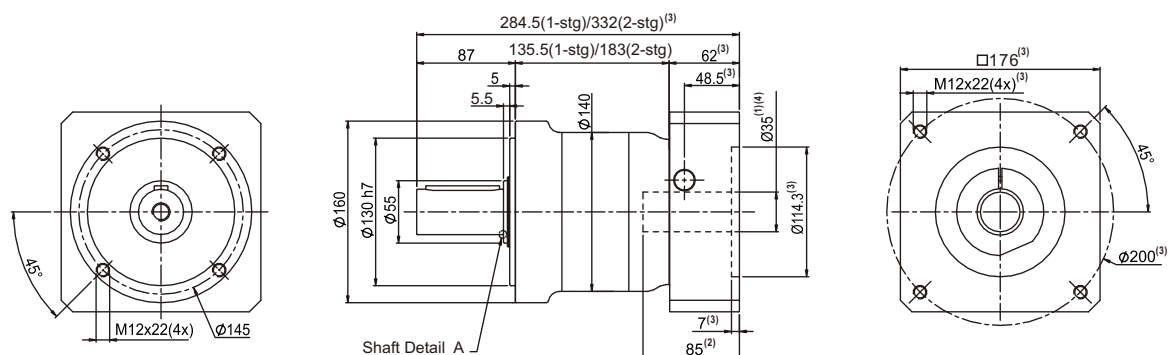
- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) $\varnothing$ = Input shaft diameter.

PGII Series Dimension

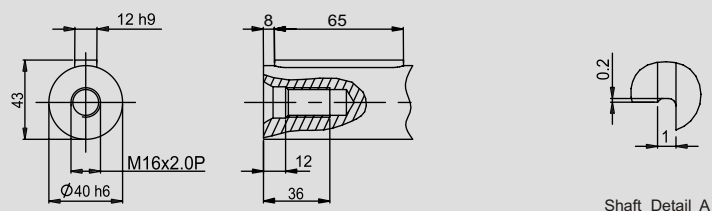
► $\emptyset^{(5)} \leq 32$



► $\emptyset^{(5)} \leq 35$



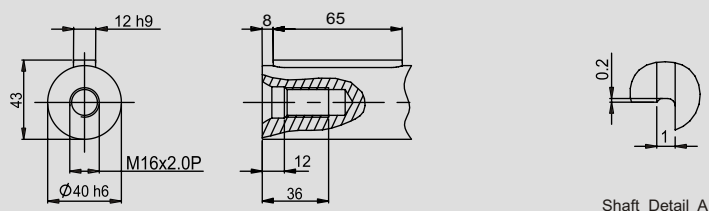
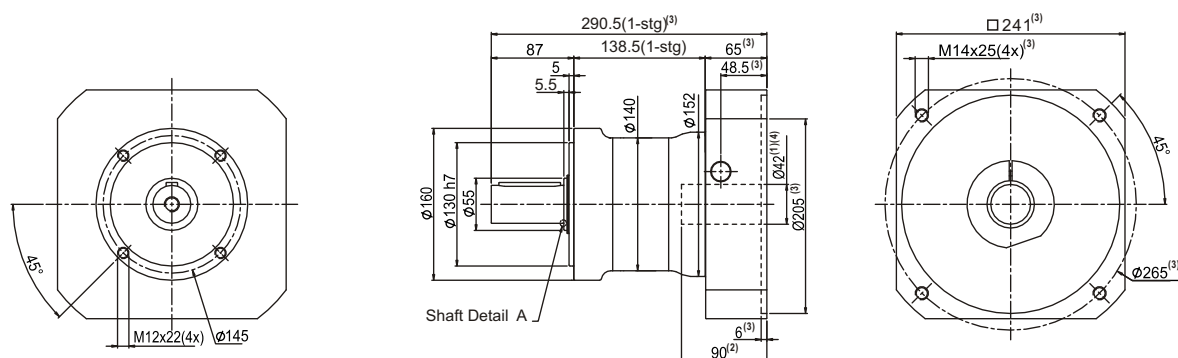
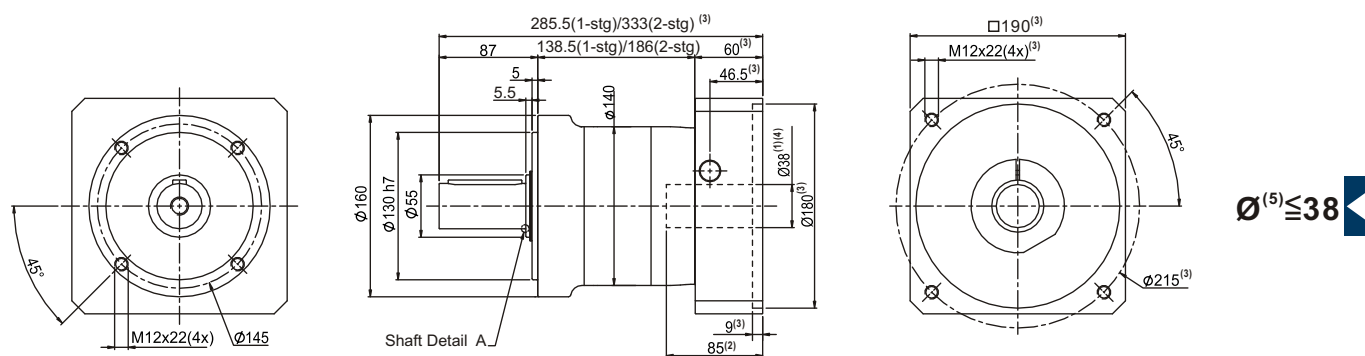
► Shaft Detail



Shaft Detail A

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) $\emptyset$ = Input shaft diameter.

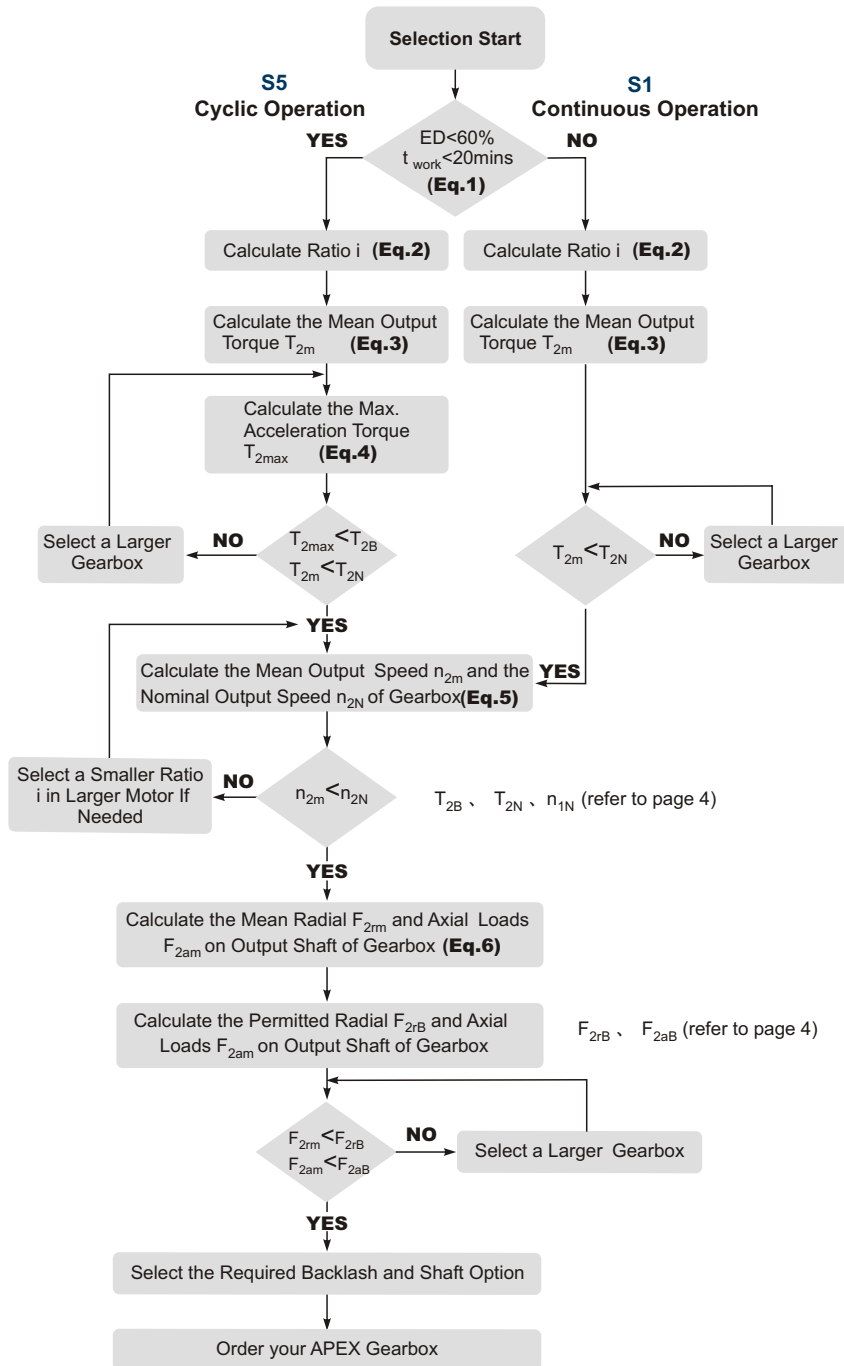
PGII Series Dimension



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø = Input shaft diameter.

Selection of the optimum gearbox



Recommended (for S5 Cycle Operation)

The general design is given for

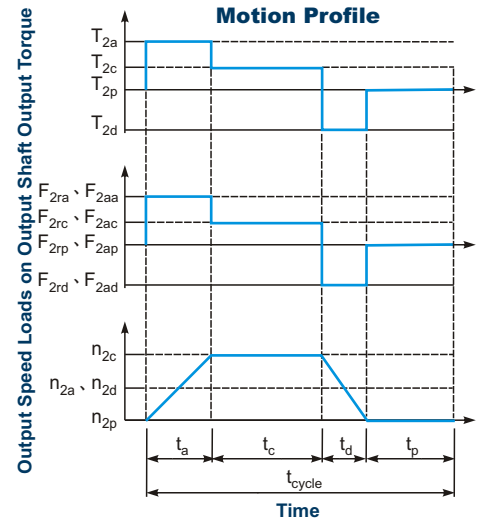
$$\frac{J_L}{i^2} \leq 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

J_L Load Inertia

J_m Motor Inertia



$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\%, t_{work} = t_a + t_c + t_d$$

Index : a. Acceleration, c. Constant,
d. Deceleration, p. Pause

(Eq.1)

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor

n_{work} Working Speed

(Eq.2)

$$3. T_{2m} = 3 \sqrt{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.3)

$$4. T_{2max} = T_{mB} \times i \times K_s \times \eta$$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2,000 ~ 3,000
1.8	3,000 ~ 5,000

T_{mB} Max. Output Torque of the Motor

η Efficiency of the Gearbox

(Eq.4)

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$

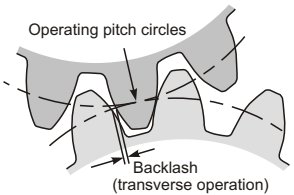
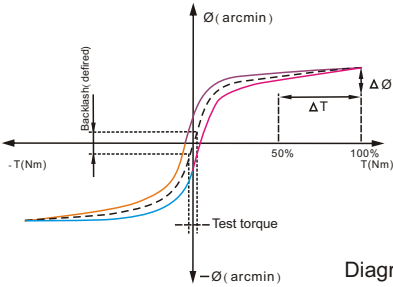
(Eq.5)

$$6. F_{2rm} = 3 \sqrt{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = 3 \sqrt{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.6)

Glossary

Emergency Stop Torque T_{2NOT}	Nm	The Emergency Stop Torque is the maximum permitted torque at the output of gearbox. This may happen only occasionally and may not exceed 1000 times during the whole service life.
Max. Acceleration Torque T_{2B}	Nm	Under the Cyclic Operation (S5), the Max. Acceleration Torque is the maximum torque which can be transmitted only briefly to the output of gearbox up to 1000 cycles/hr.
No Load Running Torque	Nm	The No Load Running Torque is the min. torque to overcome the internal friction of a gearbox without loading*.
Nominal Input Speed n_{1N}	rpm	The Nominal Input Speed is the permitted input speed of gearbox by the Continuous Operation (S1) while the housing temperature does not exceed 90°C. This value is measured at environment temperature 25°C.
Max. Input Speed n_{1B}	rpm	The Max. Input Speed is the max. permitted input speed of gearbox by the Cyclic operation (S5). This value is measured at environment temperature 25°C and serves as the absolute limit of the gearbox.
Backlash	arcmin	The Backlash is the maximum angular measurement between two teeth of gears when the transverse operation occurs (refer to Diagram 1). The arcmin is the measurement unit for the backlash. One arcmin equals 1/ 60 degree, symbolized as 1'.  Diagram 1
Torsional Rigidity	Nm/arcmin	Torsional Rigidity is the quotient ($\Delta T / \Delta \varnothing$) between the applied torque and resulting torsion angle. This value indicates how many torque needed on gearbox to rotate the output shaft for 1 arcmin. The Torsional Rigidity can be determined by Hysteresis Curve. Hysteresis Curve When the input shaft is locked, increase torque at the output slowly up to T_{2B} in both directions and then release the torque gradually. According to the measured torque and torsion angle, a closed curve will be acquired as Diagram 2.  Diagram 2
Efficiency η	%	The transmission efficiency of the gears inside a gearbox (without friction).
Operating Temperature	° C	The Operating Temperature indicates the temperature of gearbox housing.
Lubrication		APEX uses synthetic lubrication grease. There are other grease available, please contact APEX.
Running Noise	dB(A)	The Running Noise is measured depends on gearbox size, the ratio and the speed*. Higher speed induces usually higher noise level, while higher ratio induces lower noise level.
Moment of Inertia J_1	kg.cm ²	The Moment of Inertia J1 is a measurement of the effort applied to an object to maintain its momentary condition at rest or rotating.
Breakaway Torque	Nm	The Breakaway Torque is the minimum torque to start the rotation from the input side of gearbox. A smaller size or a higher ratio gearbox requests less Breakaway Torque.
Back Driving Torque	Nm	The Back Driving Torque is the minimum torque to start the rotation from the output side of gearbox. A larger size or a higher ratio gearbox requests greater Back Driving Torque.

* This value is measured at environment temperature 25°C and the input speed 3000 rpm. If the Nominal Input Speed n_{1N} of gearbox is over 3000 rpm, this value is measured by that specific Nominal Input Speed.

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